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Spatial disaggregation of activity data for GHG inventory in agricultural sector of Poland

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Abstract

This report presents a novel approach for allocation of spatially correlated data, such as emission inventories, to finer spatial scales, conditional on covariate information observable in a fine grid. Spatial dependence is modelled with the conditional autoregressive structure introduced into a linear model as a random effect. The maximum likelihood approach to inference is employed, and the optimal predictors are developed to assess missing values in a fine grid. The usefulness of the proposed technique is shown for agricultural sector of GHG inventory in Poland. An example of allocation of livestock data (a number of horses) from district to municipality level is analysed. The results indicate that the proposed method outperforms a naive and commonly used approach of proportional distribution.

Keywords: GHG inventory, agricultural sector, spatial correlation, disaggregation, conditional autoregressive model

Chapter 1

Introduction

Greenhouse gas (GHG) emission inventories serve as a basic tool for verification of international treaties aimed at constraing global warming. Despite all their drawbacks and limitations [14], national GHG inventories provide invaluable information on anthropogenic emission sources, and, indirectly, on effectiveness of undertaken emission abatement measures. Constant efforts of IPCC community seek to improve the inventory procedure and to limit underlying uncertainties and imprecision [13].

Although the greenhouse gases directly are not harmful for human health, their spatial distribution is of great importance. For instance, a network of ecosystem long-term observation sites is launched across Europe to understand behavior of the global carbon cycle and greenhouse gas emissions. The activities are conducted within the Integrated Carbon Observation System infrastructure. Another approach is to develop a spatially resolved GHG inventory. All of these efforts open new opportunities for improvement of emission reduction activities, including among others attribution of sources and sinks.

The present study was conducted as a part of the 7FP Marie Curie Actions project *Geoinformation technologies, spatio-temporal approaches, and full carbon account for improving accuracy of GHG inventories.* One of the main aims of the project is to develop a spatial inventory of GHG for Poland. The task comprises estimation of GHG related activity data, which need to be spatially resolved in this case, and their corresponding emission factors. In terms of considered sectors, subsectors and separate emission source groups, the IPCC guidelines [11] provide relevant methodology, and it is followed throughout the project. The main GHG emission sectors include energy (fossil fuel burning from stationary and mobile sources), industry and agriculture.

Development of spatial GHG inventory crucially depends on availability of low resolution activity data. In Poland, relevant information needs to be acquired from national/regional totals. A procedure of allocation into smaller spatial units (like districts, municipalities and finally 2x2km grid) differs among various emission sectors. Basically, all the emission sources are categorised as line, area or large point emission sources; further steps differ significantly for each group. For large point sources, such as power/heat stations or refinery plants, corresponding emissions are associated directly with a particular object located in space. Line sources, like roads, railways or pipelines, are usually analyzed by cutting line objects into sections using respective grids. Area sources comprise e.g. agricultural fields, urban areas as well as highly dense urban transportation network. In this case, a procedure of spatial allocation depends on methods and technologies of fossil fuel combustion in a considered sector [2]. A common approach though is a spatial allocation made in a proportion to some related indicators, i.e. proxy data, which are available in a finer grid. This solution to a large extent relies on subjective assumptions, and usually there is no mean for verification of the results obtained.

Within the project Work Package 3, the statistical scaling methods are developed in order to support the procedure of compiling high resolution activity data. In this report we propose the method for allocating GHG activity data to finer spatial scales conditional on covariate information, such as land use, observable in a fine grid. The proposition is suitable for spatially correlated, area emission sources.

The approach resembles to some extent the method of Chow and Lin (1971) [3], originally proposed for disaggregation of time series based on related, higher frequency series. Here, a similar methodology is employed to disaggregate spatially correlated data. Regarding an assumption on residual covariance, we apply the structure suitable for area data, i.e. the conditional autoregressive (CAR) model. Although the CAR specification is typically used in epidemiology [1], it was also successfully applied for modelling air pollution over space [12], [15]. Compare also [9] for another application of the CAR structure to model spatial inventory of GHG emissions. The maximum likelihood approach to inference is employed, and the optimal predictors are developed to assess missing concentrations in a fine grid. We demonstrate usefulness of the disaggregation method for spatially correlated area sources, in particular for agricultural sector.

A part of the methododology described in section 3.1 was already presented in [10]. This contribution extends the basic model for the case of various regression models in each region (here voivodeship); see section 3.2. Performance of the method for livestock data in agricultural sector of GHG inventory is presented in chapter 4.

Chapter 3

The disaggregation framework

3.1 The basic model

We begin with the model specification in a fine grid. Let Y_i denote a random variable associated with a missing value of interest y_i defined at each cell *i* for i = 1, ..., n of a fine grid (*n* denotes the overall number of cells in a fine grid). Assume that each random variable Y_i follows Gaussian distribution with the mean μ_i and variance σ_Y^2

$$Y_i | \mu_i \sim \mathcal{N}\left(\mu_i, \sigma_Y^2\right). \tag{3.1}$$

Given the values μ_i and σ_Y^2 , the random variables Y_i are assumed independent. The values $\mu = \{\mu_i\}_{i=1}^n$ represent the true process underlying distribution of activity data in our case study, and the (missing) observations are related to this process through a measurement error of variance σ_Y^2 . The model for the underlying process μ is formulated as a sum of regression component with available covariates, and a spatially varying random effect.

Spatial correlation is modelled with the conditional autoregressive structure CAR. Following an assumption of similar random effects in adjacent cells, it is given through the specification of full conditional distribution functions [4], [6]

$$\mu_i | \mu_{j,j \neq i} \sim \mathcal{N}\left(\boldsymbol{x}_i^T \boldsymbol{\beta} + \rho \sum_{j \neq i} \frac{w_{ij}}{w_{i+}} \left(\mu_j - \boldsymbol{x}_j^T \boldsymbol{\beta}\right), \frac{\tau^2}{w_{i+}}\right), \ i, j = 1, ..., n$$
(3.2)

where w_{ij} are the adjacency weights; w_{i+} is the number of neighbours of area i; $x_i^T \beta$ is a regression component with explanatory covariates for area i and a respective vector of regression coefficients, and τ^2 is a variance parameter. The joint distribution of the process μ is [4], [6]

$$\boldsymbol{\mu} \sim \mathcal{N}_{\boldsymbol{n}} \left(\boldsymbol{X} \boldsymbol{\beta}, \tau^2 \left(\boldsymbol{D} - \rho \boldsymbol{W} \right)^{-1} \right), \qquad (3.3)$$

where X is a design matrix with vectors x_i ; D is an $n \times n$ diagonal matrix with w_{i+} on the diagonal; and W is an $n \times n$ matrix with adjacency weights w_{ij} . Equivalently, we can write (3.3) as $\mu = X\beta + \epsilon$, $\epsilon \sim \mathcal{N}_n(\mathbf{0}, \mathbf{N})$, with $\mathbf{N} = \tau^2 (\mathbf{D} - \rho \mathbf{W})^{-1}$.

The model for the data observed at the district level is obtained by the multiplication of μ with an $N \times n$ aggregation matrix C, where N is a number of observations on the district level

$$C\mu = CX\beta + C\epsilon, \quad C\epsilon \sim \mathcal{N}_N(\mathbf{0}, CNC^T).$$
 (3.4)

The matrix C consists of 0's and 1's, indicating which cells have to be aligned together. The random variable $\lambda = C\mu$ is treated as the mean process for variables $Z = \{Z_i\}_{i=1}^N$ associated with observations $z = \{z_i\}_{i=1}^N$ of the aggregated model

$$Z|\lambda \sim \mathcal{N}_N\left(\lambda, \sigma_Z^2 I_N\right).$$
 (3.5)

Also at this level, the underlying process λ is related to Z through a measurement error with variance σ_Z^2 .

The parameters β . σ_Z^2 , τ^2 and ρ are estimated with the maximum likelihood method based on the joint unconditional distribution

$$\boldsymbol{Z} \sim \mathcal{N}_{\boldsymbol{N}}\left(\boldsymbol{C}\boldsymbol{X}\boldsymbol{\beta}, \boldsymbol{M} + \boldsymbol{C}\boldsymbol{N}\boldsymbol{C}^{T}\right),$$

where $M = \sigma_z^2 I_N$. The analytical derivation is limited to the regression coefficients β , and further maximisation of the profile log likelihood is performed numerically. The standard errors of estimators are calculated with the expected Fisher information matrix.

Regarding the missing values of a number of horses in municipalities, the underlying process μ is of our primary interest. The predictors optimal in terms of the minimum mean squared error are given by $E(\mu|z)$. The joint distribution of (μ, Z) is

$$\begin{bmatrix} \mu \\ Z \end{bmatrix} \sim \mathcal{N}_{n+N} \left(\begin{bmatrix} X\beta \\ CX\beta \end{bmatrix}, \begin{bmatrix} N & NC^T \\ CN & M+CNC^T \end{bmatrix} \right).$$
(3.6)

The distribution (3.6) allows for full inference, yielding both the predictor and its error

$$\widehat{E(\boldsymbol{\mu}|\boldsymbol{z})} = \boldsymbol{X}\widehat{\boldsymbol{\beta}} + \widehat{\boldsymbol{N}}\boldsymbol{C}^{T}\left(\widehat{\boldsymbol{M}} + \boldsymbol{C}\widehat{\boldsymbol{N}}\boldsymbol{C}^{T}\right)^{-1}\left[\boldsymbol{z} - \boldsymbol{C}\boldsymbol{X}\widehat{\boldsymbol{\beta}}\right]$$

$$\widehat{Var(\boldsymbol{\mu}|\boldsymbol{z})} = \widehat{\boldsymbol{N}} - \widehat{\boldsymbol{N}}\boldsymbol{C}^{T}\left(\widehat{\boldsymbol{M}} + \boldsymbol{C}\widehat{\boldsymbol{N}}\boldsymbol{C}^{T}\right)^{-1}\boldsymbol{C}\widehat{\boldsymbol{N}}.$$

3.2 A modification: Various regression models in regions

Next, we adjust the model to reflect possibly diversified regression component across regions. In the considered study of national GHG inventory, we will analyse various regression models for 16 voivodeships indexed with $l = 1, \ldots, L$. Then, all *n* municipalities are associated with their corresponding voivodeship *l*, and let n_l denote a number of municipalities in a region *l*

$$n=\sum_{l=1}^L n_l.$$

To accommodate the modification, consider a block diagonal matrix of covariates X^* , where each block corresponds to a region l = 1, ..., L and contains covariates only for municipalities of this region

$$\boldsymbol{X^*} = \begin{bmatrix} 1 & x_{11}^1 & \cdots & x_{1k}^1 & & & \\ \vdots & \ddots & \vdots & & & \\ 1 & x_{n_{11}}^1 & & x_{n_{1k}}^1 & & & \\ & & & \ddots & & \\ & & & & 1 & x_{11}^L & \cdots & x_{1k}^L \\ & & & & & 1 & x_{n_{11}}^L & \cdots & x_{n_{nk}}^L \end{bmatrix}$$

Also a vector of regression coefficients needs to be modified into β^* , comprising separate sets of regression coefficients for each region

$$\boldsymbol{\beta^{*}} = \begin{bmatrix} \beta_{0}^{L} \\ \vdots \\ \beta_{k}^{L} \\ \vdots \\ \beta_{0}^{L} \\ \vdots \\ \beta_{k}^{L} \end{bmatrix}$$

and the process μ is redefined as

$$\mu = X^*\beta^* + \epsilon, \ \epsilon \sim Gau_n(0,\Omega).$$

To complete the setting, variance parameters $(\sigma_{Y,l})^2$ and $(\sigma_{Z,l})^2$ are introduced for each region $l = 1, \ldots, L$.

Chapter 5

Concluding remarks and discussion

The study presents the first attempt to apply the spatial scaling model for the GHG inventory in Poland. The task was to allocate spatially correlated data to finer spatial scales, conditional on covariate information observable in a fine grid. Spatial dependence is set and it is assumed not to change with the change of grid. It is modelled with the conditional autoregressive structure introduced into a linear model as a random effect. The maximum likelihood approach to inference is employed, and the optimal predictors are developed to assess missing values in a fine grid. The usefulness of the proposed technique is shown on an example of allocation of livestock data (a number of horses) from district to municipality level.

The results of the disaggregation with the proposed procedure were compared with the allocation proportional to population of municipalities. An improvement over the naive, proportional approach of 9% in terms of the mean squared error was reported. In addition, we extended the model to allow for various regression models in regions (here voivodeships). Numerous features of the proposed method require further investigation.

The proposed method provided good results for livestock activity data of agricultural sector. Apart from the reported above study, the approach was also applied in a residential sector for disaggregation of natural gas consumption in households. In that case, with disaggregation featured from voivodeships into municipalities, the results turned to be quite modest. This was partly due to limited spatial correlation of the analysed process and too large extent of disaggregation. The method is feasible for disaggregation from districts into municipalities, but not from voivodeships into municipalities.

It should be stressed that the primary asset of the proposed approach is the possibility to asses significance of considered regression coefficients. The widely used proportional distribution of activity data can be based only on expert judgements, providing no means for outcome verification.

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Appendix

Table 5.1: List of voivodships

l	Voivodship
1	Dolnośląskie
2	Kujawsko-Pomorskie
3	Lubelskie
4	Lubuskie
5	Łódzkie
6	Małopolskie
7	Mazowieckie

- 8 Opolskie
- 9 Podkarpackie
- 10 Podlaskie
- 11 Pomorskie
- 12 Śląskie
- 13 Swiętokrzyskie
- 14 Warmińsko-Mazurskie
- 15 Wielkopolskie
- 16 Zachodniopomorskie