

## NOTES AND REFERENCES.

518. RIBAUCCOUR, *C. R.*, t. LXXV. (1872), pp. 533—536, referring to my Note remarks that the condition can be (by means of the imaginary coordinates of M. Ossian Bonnet) expressed in a simple form communicated by him to the Philomathic Society, May, 1870. I reproduce this investigation, although it is not easy to present it in a quite intelligible form. We take  $p=f(x, y, z)$  to represent a family of surfaces belonging to a triply orthotomic system, and consider two neighbouring surfaces ( $A$ ) and ( $A'$ ) corresponding to the values  $z$  and  $z+dz$ ;  $A$  and  $A'$  the two points where they meet the trajectories of the surfaces;  $AT, A'T'$  the tangents to the curves of curvature of the same system at  $A, A'$  respectively. Then according to the remark of M. Lévy, it is to be expressed that these lines meet, and this is done by expressing that *along the trajectory  $AA'$ , the variation of the angle of  $AT$  with the osculating plane at  $A$  is equal to the angle of the osculating planes at  $A, A'$  respectively.*

Let  $B'$  be the spherical image of  $A'$ , the plane  $OBB'$  is parallel to the osculating plane at  $A$  of the trajectory, and the angle of the two osculating planes measures the geodesic curvature of  $BB'$ : denote this by  $d\gamma$ .

Let  $\beta$  be the angle of  $BB'$  with  $BX$ ,  $\theta$  the angle of  $AT$  with  $BX$ ,  $\beta-\theta$  is the angle of  $AT$  with the osculating plane at  $A$  of the trajectory:  $d\beta-d\theta=d\gamma$ . Introducing the symmetric imaginary coordinates  $x$  and  $y$ , we write

$$a = \frac{dp}{\lambda^2 dx}, \quad b = \frac{dp}{\lambda^2 dy}, \quad c = \frac{1}{\lambda^2} \frac{d^2p}{dx dy}, \quad ds^2 = 4\lambda^2 \frac{da}{dx} \frac{db}{dy} dx dy.$$

But  $dx$  and  $dy$  being the increments of  $x, y$  corresponding to  $dz$  in the passage from  $A$  to  $A'$ , then by a theorem of M. Liouville

$$d\gamma = d\beta - i \left( \frac{d\lambda}{\lambda dx} dx - \frac{d\lambda}{\lambda dy} dy \right);$$

the condition thus is

$$d\theta = i \left( \frac{d\lambda}{\lambda dx} dx - \frac{d\lambda}{\lambda dy} dy \right),$$

and the formula

$$e^{-2i\theta} = \pm \sqrt{\frac{d\bar{a}}{dx} \div \frac{d\bar{b}}{dy}},$$

enables this to be written in the definitive form

$$dx \frac{d}{dx} l \left( \lambda^4 \frac{db}{dy} \div \frac{da}{dx} \right) + dy \frac{d}{dy} l \left( \frac{db}{dy} \div \lambda^4 \frac{da}{dx} \right) + dz \left\{ \frac{d}{dz} \left( l \frac{db}{dy} \right) - \frac{d}{dz} \left( l \frac{da}{dx} \right) \right\} = 0.$$

We have

$$dx \left( \frac{1}{2}p + c \right) + dy \frac{db}{dy} + dz \frac{db}{dz} = 0,$$

$$dx \frac{da}{dx} + dy \left( \frac{1}{2}p + c \right) + dz \frac{da}{dz} = 0,$$

and thence eliminating  $dx$ ,  $dy$ ,  $dz$ , we have

$$\left| \begin{array}{ccc} \frac{d}{dx} l \left( \lambda^4 \frac{db}{dy} \div \frac{da}{dx} \right), & \frac{d}{dy} l \left( \frac{db}{dy} \div \lambda^4 \frac{da}{dx} \right), & \frac{d}{dz} l \left( \frac{db}{dy} \div \frac{da}{dx} \right) \\ \frac{1}{2}p + c, & \frac{db}{dy}, & \frac{db}{dz} \\ \frac{da}{dx}, & \frac{1}{2}p + c, & \frac{da}{dz} \end{array} \right| = 0,$$

which defines the triply orthotomic system.

END OF VOL. VIII.

