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ON THE SIGNIFICATION OF AN ELEMENTARY FORMULA OF SOLID GEOMETRY.

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THE expression for the perpendicular distance of a point  $(x, y, z)$  from a line through the origin inclined at the angles  $(\alpha, \beta, \gamma)$  to the three axes respectively, is

$$\begin{aligned} p^2 &= x^2 + y^2 + z^2 - (x \cos \alpha + y \cos \beta + z \cos \gamma)^2 \\ &= (y \cos \gamma - z \cos \beta)^2 \\ &\quad + (z \cos \alpha - x \cos \gamma)^2 \\ &\quad + (x \cos \beta - y \cos \alpha)^2; \end{aligned}$$

and the remark in reference to it is that, if at the given point  $P$  we draw, perpendicular to the plane through  $P$  and the given line, a distance  $PK$  equal to the distance of  $P$  from the given line, then the expressions

$$y \cos \gamma - z \cos \beta, \quad z \cos \alpha - x \cos \gamma, \quad x \cos \beta - y \cos \alpha,$$

which enter into the preceding formula, denote respectively the coordinates of the point  $K$  referred to  $P$  as origin.

If the given line instead of passing through the origin pass through the point  $x_0, y_0, z_0$ , then the corresponding expressions are of course

$$(y - y_0) \cos \gamma - (z - z_0) \cos \beta, \quad (z - z_0) \cos \alpha - (x - x_0) \cos \gamma, \quad (x - x_0) \cos \beta - (y - y_0) \cos \gamma,$$

and if we denote the "six coordinates" of the given line, viz.

$$\cos \alpha, \quad \cos \beta, \quad \cos \gamma, \quad y_0 \cos \gamma - z_0 \cos \beta, \quad z_0 \cos \alpha - x_0 \cos \gamma, \quad x_0 \cos \beta - y_0 \cos \gamma,$$

by

$$a, \quad b, \quad c, \quad f, \quad g, \quad h$$

respectively (so that  $af + bg + ch = 0$ ), then the three expressions become

$$cy - bz - f, \quad az - cx - g, \quad bx - ay - h$$

respectively.

It is moreover clear that if the point  $P$  be moved to  $P'$  by an infinitesimal rotation  $\omega$  about the given line, then  $P'$  lies on the line  $PK$  at a distance  $PP' = \omega PK$ , from the point  $P$ , and the displacements of  $P$  in the directions of the axes are consequently equal to

$$\omega (cy - bz - f), \quad \omega (az - cx - g), \quad \omega (bx - ay - h)$$

respectively, which is a fundamental formula in the theory of the infinitesimal rotations of a solid body.

Cambridge, October 26, 1865.