836. 

## ON THE QUATERNION EQUATION $q Q-Q q^{\prime}=0$.

[From the Messenger of Mathematics, vol. xiv. (1885), pp. 108-112.]

I consider the equation $q Q-Q q^{\prime}=0$, where $q, q^{\prime}$ are given quaternions, and $Q$ is a quaternion to be determined. Obviously a condition must be satisfied by the given quaternions; for, substituting in the given equation for $q, q^{\prime}, Q$ their values, say $w+i x+j y+k z, w^{\prime}+i x^{\prime}+j y^{\prime}+k z^{\prime}$, and $W+i X+j Y+k Z$ respectively, and equating to zero the scalar part and the coefficients of $i, j, k$, we have four equations linear in $W, X, Y, Z$, and then eliminating these quantities, we have the condition in question. Supposing the condition satisfied, the ratios of $W, X, Y, Z$ are then completely determined, and the required quaternion $Q$ is thus determinate except as to a scalar factor, or say $Q$ is = product of an arbitrary scalar into a determinate quaternion expression.

It might, at first sight, appear that the condition is that the given quaternions shall have their tensors equal, $T q=T q^{\prime}$; for the equation gives $T q \cdot T Q-T Q \cdot T q^{\prime}=0$, that is, $T Q\left(T q-T q^{\prime}\right)=0$. But we cannot thence infer, and it is not true, that the condition is $T q-T q^{\prime}=0$; the formula does not give the required condition at all, but the conclusion to which it leads is that, when the condition is satisfied, then in general (that is, unless $T q-T q^{\prime}=0$ ) the required quaternion is an imaginary quaternion (or, as Hamilton calls it, a biquaternion) having its tensor $T Q=0$. In the particular case where the given quaternions are such that $T q-T q^{\prime}=0$, then the required quaternion $Q$ is determined less definitely, viz. it becomes = product of an arbitrary scalar into a not completely determined quaternion expression; and it is thus in general such that $T Q$ is not $=0$. In explanation, observe that, for the particular case in question, the four linear equations for $W, X, Y, Z$ reduce themselves to two independent relations, and they give therefore for the ratios of $W, X, Y, Z$ expressions involving an arbitrary parameter $A$; these expressions cannot, it is clear, be deduced from the determinate expressions which belong to the general case.

Instead of directly working out the condition in the manner indicated above, I present the investigation in a synthetic form as follows:

Taking $v, v^{\prime}$ for the vector parts of the two given quaternions, so that $q=w+v$, $q^{\prime}=w^{\prime}+v^{\prime}$, I write for shortness

$$
\begin{aligned}
& \theta=\quad w-w^{\prime}, \\
& \alpha=\quad v^{2}+v^{\prime 2}, \quad=-x^{2}-y^{2}-z^{2}-x^{\prime 2}-y^{\prime 2}-z^{\prime 2}, \\
& \beta=\quad v^{2}-v^{\prime 2}, \quad=-x^{2}-y^{2}-z^{2}+x^{\prime 2}+y^{\prime 2}+z^{\prime 2}, \\
& D=-\theta\left(\alpha-\theta^{2}\right), \\
& A=\quad \beta-\theta^{2}, \\
& B=\quad \beta+\theta^{2} ;
\end{aligned}
$$

so that $\theta, \alpha, \beta, D, A, B$ are all of them scalars. With these I form a quaternion $Q=(D+A v)\left(D+B v^{\prime}\right) ;$ I say that we have identically

$$
q Q-Q q^{\prime}=\left\{D-v \cdot v^{\prime 2}+v^{\prime} \cdot v^{2}+v v^{\prime} \cdot \theta\right\}\left(\theta^{4}-2 \alpha \theta^{2}+\beta^{2}\right) .
$$

It of course follows that, if $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$, then $q Q-Q q^{\prime}=0$, viz. $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$ is the condition $\Omega=0$, for the existence of the required quaternion; and this condition being satisfied, then (omitting the arbitrary scalar factor) the value of the quaternion is $Q=(D+A v)\left(D+B v^{\prime}\right)$, a value giving $T(Q)=0$, that is, $W^{2}+X^{2}+Y^{2}+Z^{2}=0$. If $\theta=0$ (that is, $w=w^{\prime}$ ), then the condition becomes $\beta=0$, that is, $x^{2}+y^{2}+z^{2}-x^{\prime 2}-y^{\prime 2}-z^{\prime 2}=0$; and these two conditions being satisfied, $Q$ ceases to have the determinate value given by the foregoing formula: it has a value involving an arbitrary parameter, and is no longer such that $W^{2}+X^{2}+Y^{2}+Z^{2}=0$.

The identical equation is at once verified; we have

$$
\begin{aligned}
q Q-Q q^{\prime}= & (w+v) Q-Q\left(w^{\prime}-v^{\prime}\right) \\
= & \theta\left(D^{2}+D A v+D B v^{\prime}+A B v v^{\prime}\right) \\
& +v\left(D^{2}+D A v+D B v^{\prime}+A B v v^{\prime}\right) \\
& -\left(D^{2}+D A v+D B v^{\prime}+A B v v^{\prime}\right) v^{\prime} \\
= & \theta D^{2}+D A v^{2}-D B v^{\prime 2} \\
& +v\left(D A \theta+D^{2}-A B v^{\prime 2}\right) \\
& +v^{\prime}\left(D B \theta+A B v^{2}-D^{2}\right) \\
& +v v^{\prime}(\theta A B+D B-D A)
\end{aligned}
$$

The first line is here $=D\left\{D \theta+A v^{2}+B v^{\prime}\right\}$, viz. the term in $\}$ is

$$
\begin{aligned}
& -\left(\alpha-\theta^{2}\right) \theta^{2}+\left(\beta-\theta^{2}\right) v^{2}-\left(\beta+\theta^{2}\right) v^{\prime 2}, \\
= & -\alpha \theta^{2}+\theta^{4}+\beta \cdot \beta-\theta^{2} \cdot \alpha, \\
= & \theta^{4}-2 \alpha \theta^{2}+\beta^{2} ;
\end{aligned}
$$

and similarly each of the other lines contains the factor $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}$, and the equation is thus seen to hold good.

The tensor of $Q$ is $=\left(D^{2}-A^{2} v^{2}\right)\left(D^{2}-B^{2} v^{\prime 2}\right)$; and we have

$$
\begin{aligned}
D^{2}-A^{2} v^{2} & =\left(\alpha-\theta^{2}\right)^{2} \theta^{2}-v^{2}\left(\beta-\theta^{2}\right), \\
& =\theta^{6}-\left(2 \alpha+v^{2}\right) \theta^{4}+\left(\alpha^{2}+2 \beta v^{2}\right) \theta^{2}-v^{2} \beta^{2},
\end{aligned}
$$

which, observing that

$$
\alpha^{2}+2 \beta v^{2}=\beta^{2}+2 \alpha v^{2} \quad \text { is }=\left(\theta^{2}-v^{2}\right)\left(\theta^{4}-2 \alpha \theta^{2}+\beta^{2}\right) ;
$$

and similarly

$$
D^{2}-B^{2} v^{\prime 2} \quad \text { is }=\left(\theta^{2}-v^{\prime 2}\right)\left(\theta^{4}-2 \alpha \theta^{2}+\beta^{2}\right) ;
$$

hence the tensor is

$$
T Q=\left(\theta^{2}-v^{2}\right)\left(\theta^{2}-v^{\prime 2}\right)\left(\theta^{4}-2 \alpha \theta^{2}+\beta^{2}\right)^{2},
$$

which, in virtue of $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$, is $=0$.
The particular case is when $T q-T q^{\prime}=0$, that is, $w^{2}-v^{2}-w^{\prime 2}+v^{\prime 2}=0$, or say $w^{2}-w^{\prime 2}=v^{2}-v^{\prime 2}$, that is, $\theta\left(w+w^{\prime}\right)=\beta$. Combining with this the general condition $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$, we find $\theta^{2}\left\{\theta^{2}-2 \alpha+\left(w+w^{\prime}\right)^{2}\right\}=0$, or in the second factor, for $\theta$ and $\alpha$ substituting their values, we have $2 \theta^{2}\left(w^{2}-v^{2}+w^{\prime 2}-v^{\prime 2}\right)=0$, that is, $2 \theta^{2}\left(T q+T q^{\prime}\right)=0$. Attending to the assumed relation $T q-T q^{\prime}=0$, the second factor can only vanish if $T q=0, T q^{\prime}=0$; hence, disregarding this more special case, the factor which vanishes must be the first factor, that is, $\theta=0$; or the equations $T q-T q^{\prime}=0$ and $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$ give $\beta=0$ and $\theta=0$, that is, we have as already mentioned $w-w^{\prime}=0$, and $x^{2}+y^{2}+z^{2}=x^{\prime 2}+y^{\prime 2}+z^{\prime 2}$, viz. the given quaternions have their scalars equal, and the squares of their vectors also equal. The equation here is $v Q-Q v^{\prime}=0$; and writing $v^{2}=v^{\prime 2}=-p^{2}$, we see at once that a solution is

$$
Q=\left(-p^{2}+v v^{\prime}\right)+A\left(v+v^{\prime}\right),
$$

where $A$ is an arbitrary scalar; in fact, with this value of $Q$, we have at once $v Q$ and $Q v^{\prime}$ each

$$
=-p^{2}\left(v+v^{\prime}\right)+A\left(-p^{2}+v v^{\prime}\right) ;
$$

and the equation $v Q-Q v^{\prime}=0$ is thus satisfied. The value of the tensor is easily found to be

$$
T Q=2\left(A^{2}+p^{2}\right)\left(p^{2}+x x^{\prime}+y y^{\prime}+z z^{\prime}\right)
$$

which is not $=0$.
In accordance with a remark in the introductory paragraphs, the solution

$$
Q=-p^{2}+v v^{\prime}+\boldsymbol{A}\left(v+v^{\prime}\right)
$$

is not comprised in the general solution. As to this, observe that, in the case in question $\theta=0, \beta=0$, we have from the general theorem the form

$$
Q=\left(-\frac{\alpha \theta}{\beta}+v\right)\left(-\frac{\alpha \theta}{\beta}+v^{\prime}\right) ;
$$

that is,

$$
Q=\frac{\alpha^{2} \theta^{2}}{\beta^{2}}+v v^{\prime}-\frac{\alpha \theta}{\beta}\left(v+v^{\prime}\right) ;
$$

in the condition $\theta^{4}-2 \alpha \theta^{2}+\beta^{2}=0$, writing $\theta=0$, we have $\frac{\beta^{2}}{\theta^{2}}=2 \alpha$, or for $\alpha$ writing its value $=-2 p^{2}$, we have $\alpha^{2}=4 p^{4}, \frac{\theta^{2}}{\beta^{2}}=-\frac{1}{4 p^{2}}$, and thence $\frac{\alpha^{2} \theta^{2}}{\beta^{2}}=-p^{2}$, and $\frac{\alpha \theta}{\beta}=\lambda p$, if $\lambda$ denote the $\sqrt{ }(-1)$ of ordinary algebra. The resulting formula is thus

$$
Q=-p^{2}+v v^{\prime}-\lambda p\left(v+v^{\prime}\right),
$$

which corresponds to the determinate value $-\lambda p$ of the constant $A$.
The foregoing solution $Q=-p^{2}+v v^{\prime}+A\left(v+v^{\prime}\right)$ may be easily identified with that given pp. 124, 125 of Tait's Elementary Treatise on Quaternions; the case there considered is that of a real quaternion, and it was therefore assumed that the two conditions $w=w^{\prime}$, and $x^{2}+y^{2}+z^{2}=x^{\prime 2}+y^{\prime 2}+z^{\prime 2}$, were each of them satisfied.

The theory of quaternions is, as is well known, identical with that of matrices of the second order; the identity is, in effect, established by the remark and footnote "Linear Associative Algebra," American Journal of Mathematics, t. iv. (1881), p. 132. Writing $x, y, z, w$ for Peirce's imaginaries $i, j, k, l$, these have the multiplication table

|  | $x$ | $y$ | $z$ | $w$ |
| :---: | :---: | :---: | :---: | :---: |
| $x$ | $x$ | $y$ | 0 | 0 |
| $y$ | 0 | 0 | $x$ | $y$ |
| $z$ | $z$ | $w$ | 0 | 0 |
| $w$ | 0 | 0 | $z$ | $w$ |

Then if $\lambda,=\sqrt{ }(-1)$, be the imaginary of ordinary algebra, and $i, j, k$ the quaternion imaginaries, the relations between $i, j, k$ and $x, y, z, w$ are

$$
\begin{array}{lcl}
x=\frac{1}{2}(1-\lambda i), & \text { or conversely } & 1=x+w, \\
y=\frac{1}{2}(j-\lambda k), & " & i=\lambda(x-w), \\
z=\frac{1}{2}(-j-\lambda k), & " & j=(y-z), \\
w=\frac{1}{2}(1+\lambda i), & " & k=\lambda(y+z) ;
\end{array}
$$

and we can thus at once express a quaternion as a linear function of the $x, y, z, w$, or a linear function of the $x, y, z, w$ as a quaternion. And we then consider
$a x+b y+c z+d w$ as denoting the matrix $\left|\begin{array}{l}a, b \\ c, d\end{array}\right|$, we obtain for the product of two matrices the ordinary formula

$$
\left|\begin{array}{cc}
a, b \\
c, d
\end{array}\right| \cdot\left|\begin{array}{cc}
a^{\prime}, b^{\prime} \\
c^{\prime}, d^{\prime}
\end{array}\right|=\left(\begin{array}{cc}
(a, b) \\
(c, d)
\end{array} \left\lvert\, \begin{array}{cc}
\left(a^{\prime}, c^{\prime}\right), & \left(b^{\prime}, d^{\prime}\right) \\
", & "
\end{array}\right.\right.
$$

viz. we have

$$
\begin{aligned}
& (a x+b y+c z+d w)\left(a^{\prime} x+b^{\prime} y+c^{\prime} z+d^{\prime} w\right)=a a^{\prime} x^{2}+b c^{\prime} y z+\& c . \\
& \quad=\left(a a^{\prime}+b c^{\prime}\right) x+\left(a b^{\prime}+b d^{\prime}\right) y+\left(c a^{\prime}+d c^{\prime}\right) z+\left(c b^{\prime}+d d^{\prime}\right) w
\end{aligned}
$$

in accordance with the formula for the product of the two matrices. Observe that, writing

$$
\begin{aligned}
A+B i+C j+D k & =A(x+w)+B \lambda(x-w)+C(y-z)+D \lambda(y+z) \\
& =a x+b y+c z+d w
\end{aligned}
$$

we have

$$
a, d, b, c=A+B \lambda, \quad A-B \lambda, \quad C+D \lambda, \quad-C+D \lambda
$$

and thence

$$
a d-b c=A^{2}+B^{2}+C^{2}+D^{2}
$$

so that the determinant of the matrix corresponds to the tensor of the quaternion.

