# Two existence theorems for a rigid heat conductor 

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Theory of Gårding operators is used to get existence theorems for boundary-value problems of a rigid heat conductor in a weak form.

Zastosowano teorię operatorów Gårdinga do wyprowadzenia w słabej postaci twierdzeń o istnieniu dla zagadnień brzegowych dotyczących sztywnego przewodnika ciepła.

Применена теория операторов Гардинга ддя вывода в слабом виде теорем существования для краевых задач, касающихся жесткого теплопроводника.

We apply two theorems given by Oden [3] to a stationary equation of a rigid heat conductor in a weak form.

Generally $\Omega$ is a bounded domain in $R^{3}$ with smooth boundary $\partial \Omega$, and $U, V$ are reflexive separable Banach spaces such that the injection $i: U \rightarrow V$ is dense, continuous and compact. By $u_{n} \rightarrow u$ we denote weak convergence $u_{n}$ to $u$ and by $U^{\prime}$ topological dual of $U .\langle\cdot, \cdot\rangle$ is duality pairing on $U^{\prime} \times U$.

We consider the problem:
For a given $f \in U^{\prime}$ find $\theta \in U$ that for any $v \in U$

$$
\begin{equation*}
\int_{\Omega} Q(X, \theta(X), \nabla \theta(X)) \cdot \nabla v(X) d X+\int_{\Omega} q(X, \theta(X)) v(X) d X=-\int_{\Omega} f(X) v(X) d X \tag{E}
\end{equation*}
$$

Here $\theta$ denotes the temperature, $f$ is a density of heat sources, $Q$ represents a vector field of flux of heat, $q$ is a scalar field of density of heat sources depending on the temperature. We assume that we know how $Q$ and $q$ depend on $X, \theta$ and $\nabla \theta$. The equation (E) was obtained from the local form of the heat equation

$$
\operatorname{DIV} Q(X, \theta(X), \nabla \theta(X))=q(X, \theta(X))+f(X)
$$

(see, e.g. Marsden-Hughes [4]).
We recall the following definitions from [3]:
Definition 1. $A: U \rightarrow U^{\prime}$ is a Gärding operator if $A$ can be expressed in the form $A(u)=$ $=\bar{A}(u, u)$, where $\bar{A}: U \times U \rightarrow U^{\prime}$ satisfies:

1. $\forall v \in U$ the map $U \ni u \rightarrow \overline{A( } u, v) \in U^{\prime}$ is a radially continuous $\left({ }^{1}\right)$ operator from $U$ into $U^{\prime}$.
2. There exists a continuous function $H: R^{+} \times R^{+} \rightarrow R^{+}, R^{+}=[0,+\infty)$, with the property

$$
\lim _{t \rightarrow 0^{+}} \frac{1}{t} H(x, t y)=0 \quad \text { for any } \quad x, y \in R^{+}
$$

$\left.{ }^{( }{ }^{1}\right) A$ is radialiy continuous if the function $R \ni t \rightarrow\langle A(u+t v), v\rangle$ is continuous for all $u, v \in U$.
such that for every $u$ and $v$ in the ball $B_{m}(0)=\left\{w \in U:\|w\|_{U}<m\right\}$ the following inequality holds:

$$
\langle\bar{A}(u, u)-\bar{A}(v, u), u-v\rangle \geqslant-H\left(m,\|u-v\|_{v}\right) .
$$

3. If $u_{n} \rightarrow u$ weakly in $U$, then for any $v, w \in U$

$$
\begin{gathered}
\left.\liminf _{n \rightarrow+\infty}\left\langle\overline{A(v,} u_{n}\right)-\bar{A}(v, u), u_{n}-u\right\rangle \geqslant 0 \\
\quad \liminf _{n \rightarrow+\infty}\left\langle\overline{A(v,} u_{n}\right)-\overline{A(v, u), w\rangle=0}
\end{gathered}
$$

Definition 2. $A: U \rightarrow U^{\prime}$ is a variational Gårding operator if $A$ can be expressed in the form $A(u)=\bar{A}(u, u)$ where $\bar{A}: U \times U \rightarrow U^{\prime}$ satisfies:

1. The condition 1. from Def. 1 holds.
2. The condition 2. from Def. 1. holds.
3. $\forall u \in U$ the map $U \ni v \rightarrow \bar{A}(u, v) \in U^{\prime}$ is a bounded operator.
4. If $u_{n} \rightarrow u$ weakly in $U$ and $\lim _{n \rightarrow \infty}\left\langle\bar{A}\left(u_{n}, u_{n}\right)-\bar{A}\left(u, u_{n}\right), u_{n}-u\right\rangle=0$, then for any $v \in U$

$$
\bar{A}\left(v, u_{n}\right) \rightarrow \bar{A}(v, u) \quad \text { weakly in } \quad U^{\prime} .
$$

5. If $u_{n} \rightarrow u$ weakly in $U$ and for any $v \in U \bar{A}\left(v, u_{n}\right)$ converges weakly to some element $f \in U^{\prime}$, then

$$
\lim _{n \rightarrow \infty}\left\langle\overline{A( }\left(v, u_{n}\right), u_{n}\right\rangle=\langle f, u\rangle
$$

We recall the two theorems which were given by Oden [3].
Theorem 1. A coercitive $\left(^{2}\right)$ bounded Gärding operator is surjective.
Theorem 2. A coercitive bounded variational Gårding operator is surjective.
These two theorems will be used to prove the existence of a solution to two problems of the equation (E).

We shall denote by $C$ a positive constant which is not necessarily the same at each occurrence. For a positive integer $p$ we denote by $p^{\prime}$ such a number that $1 / p+1 / p^{\prime}=1$. We shall supress the dependence on $X$ in notations.

We denote by $\|\cdot\|_{W_{0}} m, p$ the norm in $W_{o}^{m, p}(\Omega)$ and by $\|\cdot\|_{p}$ the norm in $L^{p}(\Omega)$.
Application 1. Let $p>2, f \in\left(W^{1, p}(\Omega)\right)^{\prime}$. We consider a stationary equation

$$
A(\theta)=f,
$$

where

$$
A: W^{1, p}(\Omega) \rightarrow\left(W^{1, p}(\Omega)\right)^{\prime}, \quad A(\theta)=\operatorname{DIV} Q(X, \theta(X), \nabla \theta(X))
$$

with the boundary condition

$$
\theta_{\mid \partial \Omega}=\theta_{0}\left(\theta_{\mid \partial \Omega}-\text { trace of } \theta\right), \quad \theta_{0} \in W^{1-\frac{1}{p}, p}(\partial \Omega)
$$

( ${ }^{2}$ ) $A$ is a coercitive operator if $\lim _{\|u\|_{U} \rightarrow+\infty} \frac{\langle A(u), u\rangle}{\|u\|_{\boldsymbol{U}}}=\infty$.

There exists $\bar{\theta} \in W^{1, p}(\Omega)$ such that $\bar{\theta}_{\partial \Omega}=\theta_{0}$ (see e.g. [5, s. VII], [6 s. VI]). If a solution $\theta$ exists, then $\bar{\theta}-\theta \in W_{0}^{1, p}(\Omega)$, so we can formulate our problem in the following form:

For a given $f \in\left(W^{1, p}(\Omega)\right)^{\prime}$ find $\theta \in W_{0}^{1, p}(\Omega)$ such that for any $v \in W_{0}^{1, p}(\Omega)$

$$
\begin{equation*}
\langle A(\bar{\theta}+\theta), v\rangle=\langle f, v\rangle . \tag{1.1}
\end{equation*}
$$

We show that if $Q$ is suitably restricted, there exists at least one solution of the problem (1.1). We assume
I. $Q(X, \theta, \nabla \theta)=Q_{0}(\nabla \theta, X)+Q_{1}(\nabla \theta, \theta, X)$, where $Q_{0}(w, X)$ is Gateaux differentiable in $w \in R^{3}$ and continuous in $X \in \Omega$ and $Q_{1}(w, d, X)$ is Gateaux differentiable in $w \in R^{3}$ and $d \in R$ and continuous in $X \in \Omega$.
II. For any $u, v \in W^{1, p}(\Omega)$ such that $u-\bar{\theta}, v-\bar{\theta} \in W_{0}^{1, p}(\Omega)$ the following inequalities hold
a.

$$
\int_{0}^{1} \frac{d Q_{0}(\nabla u+t \nabla v, X)}{d t} d t \cdot \nabla v \geqslant a_{1}|\nabla v|^{p} \quad \text { for } \quad X \in \Omega,
$$

b.

$$
\left|Q_{0}(w, X)\right| \leqslant b_{1}\left(|w|^{p-1}+1\right) \quad \text { for } \quad w \in R^{3}, \quad X \in \Omega .
$$

III. For any $w \in R^{3}, \theta \in W^{1, p}(\Omega), X \in \Omega$
a.

$$
\left|Q_{1}(w, \theta, X)\right| \leqslant a_{2}\left(1+|\theta|^{q}+|w|^{q}\right),
$$

b.

$$
\left|\frac{\partial Q_{1}}{\partial \theta}(w, \theta, X)\right| \leqslant b_{2}\left(1+|\theta|^{q-1}+|w|^{q-1}\right),
$$

c.

$$
\forall a \in R^{3}, \quad \frac{\partial Q_{1}}{\partial w}(w, \theta, X) \cdot a \cdot a \leqslant 0 .\left(^{3}\right)
$$

In these conditions $a_{1}, b_{1}, a_{2}, b_{2}$ are positive constants and $0<q<p-1$.
Theorem 1.1. Suppose the assumptions I, II, III are fulfilled. Then there exists at least one solution of the problem (1.1).

Proof. We shall show that $A_{1}(v)=A(\bar{\theta}+v)$ is a bounded coercitive Gårding operator from $W_{0}^{1, p}(\Omega)$ into $\left(W_{0}^{1, p}(\Omega)\right)^{\prime}$. We have $W_{0}^{1, p} \subset L^{p}(\Omega)$ and the imbedding is dense continuous and compact, so the assumptions about spaces $U, V$, are fulfilled.

Step 1. $A_{1}$ is bounded.
For $u, v \in W_{0}^{1, p}(\Omega)$ we have

$$
\langle A(\bar{\theta}+u), v\rangle=\int_{\Omega} Q_{0}(\nabla \bar{\theta}+\nabla u, X) \cdot \nabla v d X+\int_{\Omega} Q_{1}(\nabla \bar{\theta}+U, \bar{\theta}+u, X) \cdot \nabla v d X .
$$

From the Hölder's inequality and the assumption IIb we have

$$
\begin{aligned}
& \left|\int_{\Omega} Q_{0}(\nabla \bar{\theta}+\nabla u, X) \cdot \nabla v d X\right| \leqslant\left\|Q_{0}(\nabla \vec{\theta}+\nabla u, X)\right\|_{p^{\prime}}\|\nabla v\|_{p} \leqslant C\left(\left\||\nabla \bar{\theta}+\nabla u|^{p-1}\right\|_{p^{\prime}}\right. \\
& \left.+\|1\|_{p^{\prime}}\right)\|v\|_{W_{0}^{1, p}} \leqslant C\left(\|\bar{\theta}+u\|_{W^{1, p}}^{p / p}+C\right)\|v\|_{W_{0}^{1, p}} \leqslant C\left(\|u\|_{W_{0}^{1, p}}^{p, p^{\prime}}+C\right)\|v\|_{W_{0}^{1, p}}
\end{aligned}
$$

${ }^{(3)}$ i.e. $\sum_{i, j=1}^{3} \frac{\partial Q_{1 j}}{\partial w_{i}}(w, \theta, X) \cdot a_{t} \cdot a_{j} \leqslant 0$.

By similar calculations we get

$$
\left|\int_{\Omega} Q_{1}(\nabla \bar{\theta}+\nabla u, \bar{\theta}+u, X) \cdot \nabla v d X\right| \leqslant C\left(\left\||\bar{\theta}+u|^{q}\right\|_{p^{\prime}}+\left\|\left||\bar{\theta}+\nabla u|^{q} \|_{p^{\prime}}+C\right) \cdot\right\| \nabla v \|_{p}\right.
$$

Since $q<p-1$, then $p^{\prime} \cdot q<p$ and we have

$$
\begin{aligned}
&\left|\int_{\Omega} Q_{1}(\nabla \bar{\theta}+\nabla u, \bar{\theta}+u, X) \cdot \nabla v d X\right| \leqslant C\left(\|\bar{\theta}+u\|_{W^{1, p}}^{q}+C\right)\|v\|_{W_{0}^{1, p}} \\
& \leqslant C\left(\|u\|_{W_{0}^{1, p}}^{q}+C\right)\|v\|_{W_{0}^{1, p}} .
\end{aligned}
$$

Taking together these two estimates we have

$$
\|A(\bar{\theta}+u)\|_{\left(W_{0}^{1, p}(\Omega)\right)^{\prime}}=\sup _{\|v\|_{W_{0}^{1, p}}}|\langle A(\bar{\theta}+u), v\rangle| \leqslant C\left(\|u\|_{W_{0}^{1, p}}^{p / p}+\|u\|_{W_{0}^{1, p}}^{q}+C\right)
$$

so $A$ is bounded.

Step 2. $A$ is a Gårding operator.
Let $\overline{A( } u, v)=A(u)+0 \cdot v$. Then $\bar{A}(u, u)=A(u)$ and the conditions 1 and 3 in Def. 1 hold because of the assumption I. We must prove the condition 2. For $u, v \in W_{0}^{1, p}(\Omega)$ we have

$$
\langle\overline{A( } \bar{\theta}+u, \bar{\theta}+u)-\bar{A}(\bar{\theta}+v, \bar{\theta}+u), u-v\rangle=J_{0}(\bar{\theta}+u, \bar{\theta}+v)+J_{1}(\bar{\theta}+u, \bar{\theta}+v),
$$

where $J_{0}$ and $J_{1}$ correspond to $Q_{0}$ and $Q_{1}$, respectively. Let us denote $z=u-v \in W_{0}^{1, p}(\Omega)$. Using the assumption IIa we get

$$
\begin{aligned}
J_{0}(\bar{\theta}+u, \bar{\theta}+v)=\int_{\Omega}\left[Q_{0}(\nabla \bar{\theta}+\nabla v+\nabla z)-Q_{0}(\nabla \bar{\theta}+\nabla v)\right] \cdot \nabla z d X & \\
& \geqslant a_{1} \int_{\Omega}|\nabla z|^{p} d X \geqslant C\|z\|_{W_{0}^{1, p}}^{p}
\end{aligned}
$$

and similarly using the assumption IIIc we obtain $(w=\bar{\theta}+v+t z)$

$$
\begin{aligned}
J_{1}(\bar{\theta}+u, \bar{\theta}+v)= & \int_{\Omega}\left[Q_{1}(\nabla \bar{\theta}+\nabla u, \bar{\theta}+u, X)-Q_{1}(\nabla \bar{\theta}+\nabla v, \bar{\theta}+v, X)\right] \nabla z d X \\
= & \int_{\Omega} \int_{0}^{1}\left[\frac{\partial Q_{1}(\nabla w, w, X)}{\partial(\nabla w)} \cdot \nabla z \cdot \nabla z+\frac{\partial Q_{1}\left(\nabla w_{0}, w, X\right)}{\partial w} z \cdot \nabla z\right] d t d X \\
& \leqslant \int_{\Omega} \int_{0}^{1} \frac{-\frac{Q_{1} w, w, X}{w} z \cdot \nabla z d t d X}{}
\end{aligned}
$$

Therefore by the assumption IIIb

$$
\begin{array}{r}
J_{1}(\bar{\theta}+u, \bar{\theta}+v) \leqslant \int_{\Omega} \int_{0}^{1}\left|\frac{\partial Q_{1}}{\partial w}(\nabla w, w, X) \cdot z \cdot \nabla z\right| d t d X \leqslant \int_{\Omega} \int_{0}^{1} b_{2}\left(1+|w|^{q-1}+|\nabla w|^{q-1}\right) \\
\times|z||\nabla z| d t d X
\end{array}
$$

We shall estimate all parts of this sum. Let $s$ denote $h=|\nabla w|^{q-1}$ and

$$
I=\int_{\Omega} \int_{0}^{1}|\nabla w|^{q-1}|z||\nabla z| d t d X
$$

Since for any $\varepsilon>0$ and any function $g$

$$
\int_{\Omega}|\nabla z||g| d X \leqslant\|z\|_{W_{0}^{1, p}}^{p} \cdot \frac{\varepsilon^{p}}{p}+\frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}\|g\|_{p^{\prime}}^{p^{\prime}}
$$

we get, taking $g=h z$,

$$
I \leqslant \int_{0}^{1} \frac{\varepsilon^{p}}{p}\|z\|_{W_{0}^{1, p}}^{p} d t+\int_{0}^{1}\|h z\|_{p^{\prime}}^{p^{\prime}} \cdot \frac{1}{p^{\prime} \varepsilon^{p^{\prime}}} d t
$$

We have also

$$
\|h z\|_{p^{\prime}}^{p^{\prime}(p-1)} \leqslant\|z\|_{p}^{p}\|h\|_{p /(p-2)}^{p} \quad \text { and } \quad\|h\|_{p /(p-2)}^{p /(p-1)}=\|\nabla w\|_{\frac{p(q-1)}{p-2}}^{\frac{p(q-1)}{p-1}} .
$$

Because $\frac{p(q-1)}{p-2}<p$, then $\|\nabla w\|_{\frac{p(q-1)}{p-2}} \leqslant C\|\nabla w\|_{p}$ and therefore for $u, v \in B_{m}(0)$ in $W_{0}^{1, p}(\Omega)$

$$
\begin{equation*}
I \leqslant \frac{\varepsilon^{p}}{p}\|z\|_{W_{0}^{1, p}}^{p}+\frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}\|z\|_{p}^{p /(p-1)} \cdot C m^{(q-1) p^{\prime}} \tag{1.2}
\end{equation*}
$$

Observing that for $u, v \in B_{m}(0) \subset W_{0}^{1, p}(\Omega)$

$$
\int_{0}^{1}\left(\|\bar{\theta}+v+t z\|_{p}\right)^{k} d t \leqslant C \int_{0}^{1} m^{k}(1+2 t)^{k} d t<\bar{C}(m)
$$

where $\bar{C}(m)$ is a constant depending only on $m$, and doing similar calculations we get

$$
\begin{equation*}
\int_{\Omega} \int_{0}^{1}|\bar{\theta}+v+t z|^{q-1}|z||\nabla z| d t d X \leqslant C \frac{\varepsilon^{p}}{p}\|z\|_{p}^{p}+\bar{C}(m) \frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}\|z\|_{p^{\prime},(p-1)}^{p} \tag{1.3}
\end{equation*}
$$

Next we have

$$
\begin{equation*}
\int_{0}^{1} \int_{\Omega}|z||\nabla z| d X d t \leqslant \frac{\varepsilon^{p}}{p}\|z\|_{W_{0}^{1_{0}^{1, p}}}^{p}+\frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}\|z\|_{p^{\prime}}^{p^{\prime}} \tag{1.4}
\end{equation*}
$$

Since $p>2$, therefore

$$
\|z\|_{p^{\prime}}^{p^{\prime}}=\int_{\Omega}|z|^{p^{\prime}} d X \leqslant C\left\||z|^{p}\right\|_{p-1} \leqslant C\|z\|_{p}^{p /(p-1)}
$$

Putting this estimate into Eq. (1.4) and taking into account Eqs. (1.2) and (1.3) we have

$$
J_{1}(\bar{\theta}+u, \bar{\theta}+v) \leqslant \frac{3 \varepsilon^{p}}{p}\|z\|_{W_{0}^{1, p}}^{p}+\bar{C}(m)\|z\|_{p}^{p /(p-1)}
$$

Combining thus with the estimate of $J_{0}$ we get

$$
J_{0}(\bar{\theta}+u, \bar{\theta}+v)+J_{1}(\bar{\theta}+u, \bar{\theta}+v) \geqslant\left(C-\frac{3 \varepsilon^{p}}{p}\right)\|z\|_{W_{0}^{1, p}}^{p}-\bar{C}(m)\|z\|_{p}^{p /(p-1)} .
$$

If we choose $\varepsilon$ such as to have $C-\frac{3 \varepsilon^{p}}{p}>0$ for $u, v \in B_{m}(0)$ we have

$$
\langle A(\bar{\theta}+u)-A(\bar{\theta}+v), u-v\rangle \geqslant-\bar{C}(m)\|u-v\|_{p}^{p /(p-1)} .
$$

Let us define

$$
H: R^{+} \times R^{+} \rightarrow R^{+}, H(x, y)=\bar{C}(x) y^{p /(p-1)} .
$$

$H$ is continuous and $\lim _{t \rightarrow 0^{+}} \frac{1}{t} H(x, t y)=0$ because $p /(p-1)>1$ for $p>2$.
Furthermore we have for $u, v \in B_{m}(0)$

$$
\langle A(\bar{\theta}+u)-A(\bar{\theta}+v), u-v\rangle \geqslant-H\left(m,\|u-v\|_{p}\right),
$$

which means that the condition 2 of Def. 1 is satisfied.

Step 3. $A$ is coercitive.

We have for $u \in W_{0}^{1, p}(\Omega)$ :

$$
\begin{aligned}
& \langle A(\bar{\theta}+u), u\rangle=\langle A(\bar{\theta}), u\rangle+J_{0}(u+\bar{\theta}, \bar{\theta})+J_{1}(u+\bar{\theta}, \bar{\theta}) \\
& \quad \geqslant\langle A(\bar{\theta}), u\rangle+C\|u\|_{W_{0}^{1, p}}^{p}+J_{1}(u+\bar{\theta}, \bar{\theta}) .
\end{aligned}
$$

Using

$$
\left\||\nabla \bar{\theta}+\nabla u|^{q+1}\right\|_{-\frac{p}{q+1}}^{\frac{p}{q+1}} \leqslant\|\bar{\theta}+u\|_{W^{1, p}}^{p} \quad \text { and } \quad\left\||\bar{\theta}+u|^{q}\right\|_{p^{\prime}}^{p^{\prime}} \leqslant C\|\bar{\theta}+u\|_{p}^{q p^{\prime}},
$$

we have from the assumptions IIb and IIIa

$$
\begin{array}{r}
\langle A(\bar{\theta}), u\rangle+J_{1}(u+\bar{\theta}, \bar{\theta})= \\
\int_{\Omega}\left[Q_{0}(\nabla \bar{\theta}, X)+Q_{1}(\nabla u+\nabla \bar{\theta}, u+\bar{\theta}, X)\right] \cdot \nabla u d X \\
\leqslant \int_{\Omega}\left[b_{1}\left(|\nabla \bar{\theta}|^{p-1}+1\right)+a_{2}\left(1+|u+\bar{\theta}|^{q-1}+|\nabla u+\nabla \bar{\theta}|^{q-1}\right)\right]|\nabla u| d X \\
\leqslant \int_{\Omega}\left[C+C\left(1+|u|^{q}+|\nabla u|^{q}\right)\right]|\nabla u| d X \leqslant \int_{\Omega}\left(C|\nabla u|+C|u|^{q}|\nabla u|+C|\nabla u|^{q+1}\right) d X \\
\leqslant C\left[\frac{\varepsilon^{p}}{p}\|u\|_{W_{0}^{1, p}}^{p}+\frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}(\operatorname{means}(\Omega))^{p^{\prime}}\right]+C \frac{q+1}{p} \varepsilon^{\frac{p}{q+1}}\|u\|_{W_{0}^{1, p}}^{p} \\
\\
\quad+\frac{1}{p^{\prime \prime} \varepsilon^{p^{\prime \prime}}}(\operatorname{means}(\Omega))^{p^{\prime \prime}}+C \frac{\varepsilon^{p}}{p}\|u\|_{W_{0}^{1, p}}^{p} \\
\\
\quad+C \frac{1}{p^{\prime} \varepsilon^{p^{\prime}}}\|u\|_{W_{0^{1}, p}^{p}} \quad \text { where } \quad p^{\prime \prime}=\frac{p}{p-q-1}, \quad \hat{p}=p^{\prime} q .
\end{array}
$$

Therefore

$$
\langle A(\bar{\theta}+u), u\rangle \geqslant C\left[\left(1-\frac{\varepsilon^{p}}{p}-\varepsilon^{\frac{p}{q+1}}\right)\|u\|_{W_{0}^{1}, p}^{p}-\|u\|_{W_{0}^{1}, p}^{\hat{p}_{p}}-1\right] .
$$

If we choose $\varepsilon$ such as to have $1-\frac{\varepsilon^{p}}{p}-\varepsilon^{\frac{p}{q+1}}>0$ we obtain

$$
\lim _{\|u\|_{W_{0}^{1, p \rightarrow+\infty}}} \frac{\langle A(\bar{\theta}+u), u\rangle}{\|u\|_{W_{0}^{1, p}}}=\infty
$$

because $p-1>\hat{p}-1$.
So $A_{1}$ is a coercitive bounded Gårding operator and we conclude from Theorem 1 that $A_{1}$ is surjective, so there exists $u \in W_{0}^{1, p}(\Omega)$ that for any

$$
v \in W_{0}^{1, p}(\Omega), \quad\langle A(\bar{\theta}+u), v\rangle=\langle f, v\rangle
$$

and $\theta=\bar{\theta}+u \in W^{1, p}(\Omega)$ satisfies $\langle A(\theta), v\rangle=\langle f, v\rangle$ for any $v \in W_{0}^{1, p}(\Omega)$ and $\left.\theta\right|_{\partial \Omega}=\theta_{0}$. Theorem 1.1 is proved.

Application 2. Let us consider the map

$$
A: W_{0}^{1 \cdot p}(\Omega) \rightarrow W^{-1 \cdot p^{\prime}}(\Omega)
$$

where $1<p<\infty$, and formulate the problem:
For a given $f \in W^{-1, p^{\prime}}(\Omega)$ find $\theta \in W_{0}^{1, p}(\Omega)$ such as to have for any $v \in W_{0}^{1, p}(\Omega)$

$$
\langle A(\theta), v\rangle=\int_{\Omega} Q(X, \theta(X), \nabla \theta(X)) \cdot \nabla v d X+\int_{\Omega} q(X, \theta(X)) \cdot v d X=-\int_{\Omega} f(X) v d X
$$

where
I. $\quad Q(X, u, v): \Omega \times R \times R^{3} \rightarrow R^{3}, \quad q(X, u): \Omega \times R \rightarrow R$
are continuous in $u \in R, v \in R^{3}$ for almost every $X \in \Omega$ and measurable in $X \in \Omega$ for every $u \in R, v \in R^{3}$.
II. There exists $k \in L^{p^{\prime}}(\Omega)$ such that for $X \in \Omega$

$$
\begin{aligned}
|Q(X, u, v)| & \leqslant C\left(|u|^{p-1}+|v|^{p-1}+|k(X)|\right) \\
|q(X, u)| & \leqslant C\left(|u|^{p-1}+|k(X)|\right) .
\end{aligned}
$$

If these assumptions hold, then we can easily verify that

$$
A: W_{0}^{1, p}(\Omega) \rightarrow W^{-1, p^{\prime}}(\Omega)=\left(W_{0}^{1, p}(\Omega)\right)^{\prime}
$$

We give now two lemmata which are simple consequences from the theorem 2.1 in Krasnosielskij [1].

Lemma 1. Let $u_{n} \rightarrow u$ strongly in $L^{p}(\Omega)$ and $v, w \in W^{1, p}(\Omega)$. Then

$$
\begin{array}{clll}
Q\left(X, u_{n}, \nabla v\right) & \rightarrow Q(X, u, \nabla v) & \text { strongly in } & \left(L^{p^{\prime}}(\Omega)\right)^{3}, \\
q\left(X, u_{n}\right) \rightarrow q(X, u) & \text { strongly in } & L^{p^{\prime}}(\Omega) .
\end{array}
$$

Lemma 2. Let $u_{n} \rightarrow u$ strongly in $W^{1, p}(\Omega), v \in L^{p}(\Omega)$. Then

$$
Q\left(X, v, \nabla u_{n}\right) \rightarrow Q(X, v, \nabla u) \quad \text { strongly in } \quad\left(L^{p^{\prime}}(\Omega)\right)^{3} .
$$

Now we can formulate an existence theorem.
Theorem 2.1. Let the assumptions I, II hold and
3. $A$ is a coercitive operator.
4. There exists $H: R^{+} \times R^{+} \rightarrow R^{+}$continuous and such that for any $x, y \in R^{+}$

$$
\lim _{t \rightarrow 0^{+}} \frac{1}{t} H(x, t y)=0
$$

and for

$$
\begin{gathered}
u, v \in B_{m}(0)=\left\{w \in W_{0}^{1, p}(\Omega):\| \|_{W_{0}^{1, p}}<m\right\} \\
{[Q(X, u, \nabla u)-Q(X, v, \nabla u)] \cdot(\nabla u-\nabla v) \geqslant-H\left(m,\|u-v\|_{p}\right) .}
\end{gathered}
$$

Then $A$ is surjective from $W_{0}^{1, p}(\Omega)$ onto $W^{-1, p^{\prime}}(\Omega)$
Proof.

Step 1. We show that $A$ is a variational Gårding operator.
Let us put $W_{0}^{1, p}(\Omega)$ as $U$ and $L^{p}(\Omega)$ as $V$ in Def. 2. We denote for $u, v, w \in W_{0}^{1, p}(\Omega)$

$$
\begin{aligned}
a_{1}(u, v, w) & =\int_{\Omega} Q(X, u, \nabla v) \cdot \nabla w d X \\
a_{0}(u, w) & =\int_{\Omega} q(X, u) w(X) d X
\end{aligned}
$$

The map $w \rightarrow a(u, v, w)=a_{1}(u, v, w)+a_{0}(u, w)$ is continuous from $W_{0}^{1, p}(\Omega)$ in $R$ for any $u, v \in W_{0}^{1, p}(\Omega)$. We define

$$
\left.\overline{A:} W_{0}^{1, p}(\Omega) \times W_{0}^{1, p}(\Omega) \rightarrow W^{-1, p}(\Omega) \quad \text { by } \quad\langle\overline{A( } v, u), w\right\rangle=a(u, v, w) .
$$

Then $\bar{A}(u, u)=A(u)$. Other conditions from Def. 2 are proved in the following way.

1. Because of Lemma $2 \lim _{t \rightarrow 0} Q\left(X, u, \nabla v_{1}+t \nabla v_{2}\right) \rightarrow Q\left(X, u, \nabla v_{1}\right)$ strongly in $\left(L^{p^{\prime}}(\Omega)\right)^{3}$, therefore for any $u \in W_{0}^{1, p}(\Omega)$ the map $v \rightarrow \bar{A}(v, u)$ is radially continuous from $W_{0}^{1 \cdot p}(\Omega)$ into $W^{-1, p^{\prime}}(\Omega)$.
2. We can check this condition easily using the assumption 4.
3. We can verify similarly to the next step of the proof that the operator $u \rightarrow A(v, u)$ is bounded for any $v \in W_{0}^{1, p}(\Omega)$.
4. Let $u, v, w, u_{n} \in W_{0}^{1, p}(\Omega), u_{n} \rightarrow u$ weakly in $W_{0}^{1, p}(\Omega)$. Then

$$
\left\langle\bar{A}\left(v, u_{n}\right), w\right\rangle=\int_{\Omega} Q\left(X, u_{n}, \nabla w\right) \cdot \nabla w d X+\int_{\Omega} q\left(X, u_{n}\right) w(X) d X .
$$

If we choose a subsequence $u_{n_{k}}, u_{n_{k}} \rightarrow u$ strongly in $L^{p}(\Omega)$, then from Lemma 1 we have $Q\left(X, u_{n_{k}}, \nabla v\right) \rightarrow Q(X, u, \nabla v)$ strongly in $\left(L^{p^{\prime}}(\Omega)\right)^{3}$ and $q\left(X, u_{n_{k}}\right) \rightarrow q(X, u)$ strongly in $L^{p^{\prime}}(\Omega)$. Thus we conclude that $\bar{A}\left(v, u_{n_{k}}\right) \rightarrow \bar{A}(v, u)$ weakly in $W^{-1, p}(\Omega)$ for any $v \in W_{0}^{1, p}(\Omega)$. Because this convergence holds for any subsequence which converges strongly in $L^{p}(\Omega)$, then we have it for the sequence $u_{n}$.
5. Let $u_{n} \rightarrow u$ weakly in $W_{0}^{1, p}(\Omega), \bar{A}\left(v, u_{n}\right) \rightharpoonup f$ weakly in $W^{-1, p^{\prime}}(\Omega)$ for $v \in W_{0}^{1, p}(\Omega)$. From Lemma 1 we have

$$
\begin{gathered}
Q\left(X, u_{n}, \nabla v\right) \rightarrow Q(X, u, \nabla v) \quad \text { strongly in } \quad\left(L^{p^{\prime}}(\Omega)\right)^{3}, \\
q\left(X, u_{n}\right) \rightarrow q(X, u) \quad \text { strongly in } \quad L^{p^{\prime}}(\Omega) .
\end{gathered}
$$

Hence

$$
a_{1}\left(u, v, u_{n}\right) \rightarrow a_{1}(u, v, u) .
$$

Using the Hölder's inequality we get from the Assumption II

$$
\left|a_{2}\left(u_{n}, u_{n}-u\right)\right| \leqslant C \mid\left\|u_{n}-u\right\|_{p} .
$$

Choosing a subsequence $u_{n_{k}} \rightarrow u$ strongly in $L^{p}(\Omega)$ we have

$$
a_{2}\left(u_{n_{k}}, u\right) \rightarrow\langle f, u\rangle-a_{1}(u, v, u)
$$

As a result we get for the sequence $u_{n}$

$$
\left\langle\bar{A}\left(v, u_{n}\right), u_{n}\right\rangle=a_{1}\left(u_{n}, v, u_{n}\right)+a_{2}\left(u_{n}, u_{n}\right) \rightarrow\langle f, u\rangle .
$$

Step 2. We must show that $A$ is a bounded operator. From the Assumption II we have

$$
\begin{aligned}
& |\langle A(u), w\rangle| \leqslant \int_{\Omega}|Q(X, u, \nabla u)| \cdot|\nabla w| d X+\int_{\Omega}|q(X, u)| \cdot|w(X)| d X \\
& \leqslant \int_{\Omega} C\left(|\nabla u|^{p-1}+|u|^{p-1}+|k|\right) \cdot|\nabla w| d X+C \int_{\Omega}\left(|u|^{p-1}+|k|\right) \cdot|w| d X \\
& \quad \leqslant C\left(\left\|\left.| | u\right|^{p-1}+|\nabla u|^{p-1}+|k|\right\|_{p^{\prime}}+\left\|\left||u|^{p-1}+|k| \|\right|_{p^{\prime}}\right)\|w\|_{w_{0}^{1, p}} .\right.
\end{aligned}
$$

Hence

$$
\|A(u)\|_{W^{-1, p^{\prime}}}=\sup _{\|w\|^{W 1, p}=}|\langle A(u), w\rangle| \leqslant C\left(\|u\|_{W_{0}^{1}, p}+\|k\|_{p, p}\right) .
$$

So $A$ is bounded from $W_{0}^{1, p}(\Omega)$ into $W^{-1 \cdot p^{\prime}}(\Omega)$. Therefore all assumptions of Theorem 2 l:old and we conclude that $A$ is surjective from $W_{0}^{1, p}(\Omega)$ onto $W^{-1 \cdot p^{\prime}}(\Omega)$.

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